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<input type="checkbox"/>	L27	(failure or brake down or brakedown) and mode and L26		609
<input type="checkbox"/>	L26	robot\$6 and control\$3 and assembl\$3 and configuration and image and calibration and operation and user		1442
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<input type="checkbox"/>	L9	robot\$6 and (semiconductor or chip or microprocessor or memory or ram or rom or ic or integrated circuit) (processing or manufatur\$3 or fabrication) and (vision or visual or camera or		1555

video) and transmit\$4

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Robotics and Automation, 1999. Proceedings. 1999 IEEE International Conference on
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2. **Proceedings. 1998 IEEE/RSJ International Conference on Intelligent Robots and Systems. Innovations in Theory, Practice and Applications (Cat. No.98CH36190)**
Intelligent Robots and Systems, 1998. Proceedings., 1998 IEEE/RSJ International Conference on
Volume 1, 13-17 Oct. 1998
IEEE CNF
3. **Robotic motion planning and manipulation in an uncalibrated environment**
Ghosh, B.K.; Tzyh Jong Tarn; Ning Xi; Zhenyu Yu; Di Xiao;
Robotics & Automation Magazine, IEEE
Volume 5, Issue 4, Dec. 1998 Page(s):50 - 57
IEEE JNL
4. **Planning and control of self-calibrated manipulation for a robot on a mobile platform**
Di Xiao; Ghosh, B.K.; Ning Xi; Tzyh-Jong Tarn;
Robotics and Automation, 1997. Proceedings., 1997 IEEE International Conference on
Volume 2, 20-25 April 1997 Page(s):1406 - 1411 vol.2
IEEE CNF
5. **Calibration free visually controlled manipulation of parts in a robotic manufacturing workcell**
Ghosh, B.K.; Tzyh-Jong Tarn; Ning Xi; Zhenyu Yu; Di Xiao;
Robotics and Automation, 1996. Proceedings., 1996 IEEE International Conference on
Volume 4, 22-28 April 1996 Page(s):3197 - 3202 vol.4
IEEE CNF
6. **A framework for vision-guided manipulation of a moving target**
Sharma, R.; Herve, J.-Y.; Cucka, P.;
Systems, Man, and Cybernetics, 1991. 'Decision Aiding for Complex Systems, Conference Proceedings., 1991 IEEE International Conference on
13-16 Oct. 1991 Page(s):213 - 218 vol.1
IEEE CNF

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